

1990

# The Study of Rotary Compressor Driven Under Low Electric Frequencies

Y. Sato

*Mitsubishi Electric Corporation*

Y. Shirafuyi

*Mitsubishi Electric Corporation*

Follow this and additional works at: <https://docs.lib.purdue.edu/icec>

---

Sato, Y. and Shirafuyi, Y., "The Study of Rotary Compressor Driven Under Low Electric Frequencies" (1990). *International Compressor Engineering Conference*. Paper 746.

<https://docs.lib.purdue.edu/icec/746>

This document has been made available through Purdue e-Pubs, a service of the Purdue University Libraries. Please contact [epubs@purdue.edu](mailto:epubs@purdue.edu) for additional information.

Complete proceedings may be acquired in print and on CD-ROM directly from the Ray W. Herrick Laboratories at <https://engineering.purdue.edu/Herrick/Events/orderlit.html>

THE STUDY OF ROTARY COMPRESSOR  
DRIVEN UNDER LOW ELECTRIC FREQUENCIES

Yutaka Sato Yoshinori Shirafuji  
Shizuoka Works, Mitsubishi Electric Corporation  
3-18-1, Oshika, Shizuoka City 422, JAPAN  
Tel.No. : 542-87-3112, Fax. No. : 542-87-3143

ABSTRACT

Rolling piston type rotary compressor has been widely used with an inverter control which changes the commercial electric frequency driving a compressor motor into various frequencies in order to give an appropriate cooling capacity to the refrigeration and air-conditioning system. However, a conventional rotary compressor of single cylinder type has a considerable problem that the performance severely decreases as its rotational speed of the motor decreases. The reason of this problem could be made clear through the research for a dual cylinder rotary compressor and the analysis for the compressor performance with its rotational-speed fluctuations.

As a result of it, some improvement methods for the performance at low electric frequency operation could become clear theoretically and experimentally. This paper shows the results mentioned above with theoretical analysis and experimental data including comparison between a single and dual cylinder rotary compressor.

NOMENCLATURE

Ic : Inertia moment of crankshaft system	$\theta$ : Crank angle
$\dot{\cdot}$ : Time differential	$\dot{\theta}$ : Velocity of crank angle
$\ddot{\theta}$ : Acceleration of crank angle	Tl : Required load torque
Tm : Motor output torque	Tg : Gas compression torque
Tv : Reaction torque	Tf : Friction torque
Tth : Friction torque of thrust bearing	Ip : Inertia moment of rolling piston
Mc : Friction moment of piston inside	Mb : Friction moment of piston edges
Wg : Bearing load for gas compression	W : Bearing load
e : Eccentricity of crank	rp : Rolling piston radius
$\alpha$ : Offset angle of rolling piston center	H : Rolling piston height
Pc : Pressure in compression chamber	$\mu$ : Friction coefficient
Ps : Pressure in suction chamber	r : Crankshaft radius
$\omega p$ : Angular velocity of piston	$\mu v$ : Friction coefficient of vane tip
Fv : Friction force at vane tip	Ff : Friction force at bearing
h : Oil-film thickness in bearing	Cr : Radius clearance
ej : Eccentricity of journal	rj : Journal radius
from the bearing center	L : Bearing Length
$\varepsilon = (ej/Cr)$ Eccentricity ratio	$\phi$ : Attitude angle of bearing
$\eta$ : Viscosity of lubrication oil	$\psi$ : Direction angle of load
$\omega j$ : Angular velocity of journal	$\omega b$ : Angular velocity of bearing
s : Slip of rotor	P : $=(d/dt)$ Differential operator
L1 : Self-inductance of stator	R1 : Resistance of stator
L2 : Self-inductance of rotor	R2 : Resistance of rotor
M : Mutual inductance between stator and rotor	
$\dot{\theta} r$ : Instantaneous rotational-speed of electrical angle	
Ids : d-axis current of stator	Iqs : q-axis current of stator
Idr : d-axis current of rotor	Iqr : q-axis current of rotor
Vds : d-axis voltage of stator	Vqs : q-axis voltage of stator
Vdr : d-axis voltage of rotor	Vqr : q-axis voltage of rotor

## INTRODUCTION

It was often noted that the rotational speed in a single-cylinder rotary compressor driven by an induction motor must influence on its performance defined as C.O.P (Coefficient Of Performance). Particularly it was a big problem that C.O.P fell down remarkably at the rotation below than 2000 R.P.M.

In this paper, some reasons bringing on this problem were discussed with dynamic analysis that the instantaneous values of motor torque, inertia torque and load torque for the compression process were solved as simultaneous equations. With this analysis, a certain way to improve C.O.P of rotary compressor under low speed rotation could be found, and it was shown in some figures that the results of simulation analysis were in approximate agreement with the results of experiment.

Consequently, it was able to say that the performance of rotary compressor driven by a frequency control system called an inverter, including a dual-cylinder rotary compressor, could be accurately estimated with this simulation analysis.

### DYNAMIC ANALYSIS FOR ROTATIONAL FLUCTUATIONS

#### (1) Basic Equation

A basic equation as a function of the crankshaft angle, in regard to the rotational-direction system, can be expressed as follows.

$$I_c \cdot \ddot{\theta} + Tl(\theta) = Tm(\dot{\theta}) \quad (1)$$

Hence,  $I_c$  is the value of inertia moment determined from the compressor specifications which consist of a distance of the eccentricity and the mass around the rotational center of the crankshaft system.  $Tm$  means motor output torque. Although  $Tm$  was treated as a constant value determined by motor characteristics with a constant slip speed so far,  $Tm(\dot{\theta})$  is considered as a function of  $\dot{\theta}$  this time. Because an inductance term in the motor characteristics equations must be influenced by the electric current fluctuations due to the required load torque fluctuations for compression process, values caused by such an influence must take into the term of  $Tm(\dot{\theta})$  here.

#### (2) Equations For The Required Load Torque

$Tl(\theta)$  means the required load torque for compression work in a defined small crankshaft angle,  $d\theta$ , and  $Tl(\theta)$  is given by the next equation.

$$Tl(\theta) = Tg(\theta) + Tv(\theta) + Tf(\theta) \quad (2)$$

Gas compression torque  $Tg$  can be expressed as following equations and pressure in compression chamber  $P_c$  and pressure in suction chamber  $P_s$  are given by experimental data here.

$$Tg = \sum_1 W_{gi} \cdot e \cdot \sin((\alpha_i + \theta_i)/2) \quad (3)$$

$$W_{gi} = (P_{ci} - P_{si}) \cdot 2r_p \cdot \sin((\alpha_i + \theta_i)/2) \cdot H \quad (4)$$

Hence,  $i = 1, 2$        $\theta_1 = \theta$        $\theta_2 = \theta + \pi$

Subscripts 1 and 2 in these equations mean the upper and lower cylinder side respectively in case of dealing with a dual-cylinder rotary compressor. For a single-cylinder one, only subscript 1 can be used in the equations.

Fig.1 and Fig.2 shows the schematic views indicating forces and moments acting on rolling piston and vane.  $F_v$ ,  $F_s$  and  $F_d$  in Fig.1 and Fig.2 are constraint forces acting on vane tip and sides. These values can be obtained by solving the equilibrium equation and the motion equation of rolling piston described as an equation (5) considering the effect of angular velocity  $\dot{\theta}$  and angular acceleration  $\ddot{\theta}$  of crankshaft.

$$I_p \cdot \ddot{\omega}_p = Mc - r_p \cdot \mu v \cdot F_v - Mb \quad (5)$$

The reaction torque  $Tv$  can be obtained as follows.

$$Tv = - \sum_1 F_{vi} \cdot e \cdot \sin(\alpha_i + \theta_i) \quad (6)$$

Hence,  $i = 1, 2$  for a single and dual cylinder rotary compressor respectively as explained in an equation (3) and (4).

The condition of bearings around the crankshaft can be reasonably assumed as fluid lubrication, and friction forces can be obtained by solving the basic equations (7) and (8) for journal bearing with a finite length under load fluctuations. In the equations the averaged velocity of crankshaft is used for simplicity. The journal bearing model discussed here are shown in Fig.3.

$$\frac{1}{rj^2} \cdot \frac{\delta}{\delta \theta} \left( \frac{hj^3}{\delta} \frac{\delta P}{\delta \theta} \right) + \frac{hj^3}{\delta} \frac{\delta^2 P}{\delta^2 \theta^2} = 6 \eta \cdot Cr \cdot [-\epsilon \{ \omega j + \omega b - 2(\dot{\phi} + \dot{\psi}) \sin \theta \} + 2 \epsilon \cdot \cos \theta \} \quad (7)$$

$$F_f = \frac{\eta \cdot \omega \cdot j \cdot rj^2 \cdot L}{Cr} \left[ \left( \frac{\omega j - \omega b}{\omega j} \right) \frac{2\pi}{\sqrt{1-\epsilon^2}} + \frac{\epsilon}{2} \left( \frac{Cr}{rj} \right)^2 \frac{W \cdot \sin \phi}{\eta \cdot rj \cdot \omega \cdot j \cdot L} + \frac{2\pi \cdot Cr \cdot \dot{\phi}}{rj \cdot \omega j} \left\{ \frac{1}{\sqrt{1-\epsilon^2}} \right\} \right] \quad (8)$$

Total friction torque Tf can be expressed as follows.

$$T_f = \sum_i F_{fi} \cdot r_i + T_{th} \quad (9)$$

Hence,  $i = 1, 2, 3$  Subscripts 1,2 and 3 in an equation (9) mean the upper, eccentric and lower bearing respectively.

Consequently, the required load torque for compression work  $T_l(\theta)$  should be expanded in Fourier series like an equation (10) in order to express  $T_l$  as a function of  $\theta$ . It is necessary to obtain  $T_m(\theta)$  and  $\theta$  with  $T_l(\theta)$  simultaneously.

$$T_l(\theta) = T_{l0} \cdot \left\{ A_0 + \sum_{n=1}^k A_n \cdot \cos(n \omega t) + \sum_{n=1}^k B_n \cdot \sin(n \omega t) \right\} \quad (10)$$

$T_{l0}$  : the maximum value of load torque

$k$  : the required number of term for appropriate solution

### (3) Equations For Motor Output Torque

An Equivalent circuit indicated in Fig.4 is generally authorized and used for analysis of a conventional induction motor. Electric current and voltage equations for dynamic analysis of induction motor can be defined as a matrix equation (11). Equation (11) is obtained by the rotational coordinates transformation called d-q=0 axis transformation usually that the rotary coordinate-system of stator with revolving magnetic field at synchronous speed of the electric frequency can be changed into the fixed coordinate-system. As a result of this transformation, the instantaneous values regarding the motor torque expressed as an equation (12) can be calculated with the instantaneous values of electric currents given by solving equation (11).

$$\begin{bmatrix} V_{ds} \\ V_{qs} \\ V_{dr} \\ V_{qr} \end{bmatrix} = \begin{bmatrix} R1+PL1 & 0 & MP & 0 \\ 0 & R1+PL1 & 0 & MP \\ MP & M \dot{\theta} r & R2+PL2 & L2 \dot{\theta} r \\ -M \dot{\theta} r & MP & -L2 \dot{\theta} r & R2+PL2 \end{bmatrix} \begin{bmatrix} I_{ds} \\ I_{qs} \\ I_{dr} \\ I_{qr} \end{bmatrix} \quad (11)$$

$$T_m(\theta) = M(I_{ds} \cdot I_{dr} - I_{qs} \cdot I_{qr}) \quad (12)$$

It is required that all equations noted above are solved simultaneously and calculations are continued until solutions are reasonably converged. In these numerical calculation, the friction coefficients are determined by the method that the calculated shaft-power agreed with that of the experimental model measured actually.

## MODELS FOR ANALYSIS AND EXPERIMENT

### (1) Main Specifications

The fundamental construction of a single and dual cylinder rotary compressor which are subjects for this study are shown in Fig.5 and Fig.6, respectively.

A dual-cylinder rotary compressor discussed here has a partition plate located between the upper and lower cylinder, and two eccentric cams located with a phase difference of 180 degrees between the two. However, mechanism for compression in each cylinder is completely as same as the case of a conventional single-cylinder rotary compressor.

A single-cylinder rotary compressor can install some flywheel which can

be adjusted and detached on the lower side of the rotor as shown in Fig.5 It is a quite useful way to investigate a relation between the compressor performance and the amount of inertia moment effecting on the rotational fluctuations. The main specifications of the models for this study are described in table 1.

Table 1 : Main Specifications

Compressor Type	Dual-Cyl.	Single-Cyl.		
Swept Volume(cm <sup>3</sup> /rev.)	13.0	12.7		
Inertia Moment(N·m)	0.434*10 <sup>-2</sup>	0.408*10 <sup>-2</sup>	0.981*10 <sup>-2</sup>	1.749*10 <sup>-2</sup>
Flywheel	Without	Without	With	With

## (2) Experimental Apparatus And Method

The experimental models of a single and dual-cylinder rotary compressor were installed in a secondary refrigerant compressor calorimeter to measure gas flow rate and required input power. Pressure in a compression and suction chamber of the cylinder were measured by small piezo type pressure transducers and strain gage type pressure transducers. Temperatures of refrigerant R-22 in the refrigeration cycle were measured with thermocouples.

Magnetic encoder type rotational-speed sensor was put in the edge of crankshaft and lower bearing, as shown in Fig.5 and Fig.6, in order to check the fluctuational values during one turn of crankshaft.

All theoretical and experimental studies in this paper were performed under a certain operating condition indicated in Table 2.

Table 2 : Operating Condition

Condensing Temperature	52 (°C)
Evaporating Temperature	5 (°C)
Return Gas Temperature	15 (°C)
Liquid Temperature	
Entering Exp. Valve	47 (°C)
Ambient Temperature	35 (°C)
Power Source	3 ∅, Variable
Freq.and Volt.Converter	Freq. and Volt.

## RESULTS OF ANALYSIS AND EXPERIMENT

The compressor performance influenced by the operating electric frequency for induction motor can be shown in Fig.7. There is a tendency that the performance decreases as the electric frequency driving a compressor motor becomes lower. Particularly in case of a single-cylinder type, the tendency is more remarkable than that of a dual-cylinder type. The rotational-speed fluctuations measured in the experiment for a single-cylinder one are in Fig.8. There is also a tendency the fluctuational values become larger as the operating electric frequency becomes lower. A relation between two tendencies mentioned above supposes that the rotational fluctuations could effect on the compressor performance.

Fig.9 shows the comparison of the experimental results with calculated results regarding the rotational fluctuations of a single and dual cylinder compressor driving at 34 Hz electric frequency. Through this comparison, theoretically analytical values agree well with the experimental values in both of a single and dual cylinder rotary compressor, and it can be said that this analysis can be used to simulate the other cases.

Fig.10 shows the instantaneous values of Tm, motor efficiency and the rotational-speed fluctuations obtained by solving a basic equation (1) on the basis of the required-load torque Tl for a conventional single-cylinder compressor driven at 34 Hz electric frequency. The rotational-speed fluctuations are expressed as a unit of electric frequency in Fig.10.

Considering a basic equation (1), it seems that the value of inertia moment Ic must influence on the rotational system, so a certain flywheel put on the rotor shown in Fig.5 in order to raise the amount of inertia moment around the crankshaft system of a single-cylinder rotary compressor. As a result of this trial

with a flywheel, the rotational-speed fluctuations could be reduced to a sufficiently low level indicated in Fig.11, and the required input power could be improved in a range of frequency less than 40 Hz as shown in Fig.12. Nevertheless, it could make clear that the input power increased in a range of frequency more than 40 Hz due to windage loss caused by the flywheel rotation in discharged gas. Fig.13 shows a relation between the motor efficiency and the driving electric frequency with the effect of flywheel as an inertia moment value.

In other words, these results can be explained from the aspect of motor characteristics in Fig.14 which indicates the instantaneous torque of motor output with the instantaneous rotational-speed. And it is obviously evident that the value of inertia moment effecting on the rotational stability against the load fluctuations must be important for a single-cylinder rotary compressor under a slow-speed rotation.

On the other hand, Fig.15 and Fig.16 explain that the motor characteristics for a dual-cylinder one driving at a low electric frequency has a small efficiency declining in comparison with a single-cylinder one, because the rotational fluctuations of a dual-cylinder one, having small load fluctuations structurally, is as small as that of a single-cylinder one having a large value of inertia moment. In addition, the performance of a dual-cylinder one can maintain high efficiency in a range of high speed rotation.

#### CONCLUSION

(1) It was made clear that a main reason why the rotary compressor performance was remarkably decreased as its rotational-speed decreased was the decline of motor efficiency caused by the rotational fluctuations during a turn of crankshaft system for compression work. The reason could be supported by the results of simulation analysis and experiment in this study.

(2) It could be found that the amount of the inertia moment about the crankshaft system was deeply related to the fluctuational values of rotation and the relationship was quantitatively studied by simulation analysis and some unique experimental methods.

(3) Dual-cylinder rotary compressor has a superior characteristics in its structure with regard to the load-torque fluctuations specially under a slow rotational-speed. In consequence of this investigation to compare a single-cylinder rotary compressor adjusting the amount of inertia moment with a dual-cylinder one, it can be made clear that a dual-cylinder type must be a suitable one to be driven by a wide range of electric frequency control in refrigeration and air-conditioning.

#### REFERENCE

- (1) T. Shiga, I. Chu, K. Ishijima and K. Sakaino, "Analysis of the rolling type rotary compressor", Proc. Purdue Compressor Tech. Conf.,1978.
- (2) K. Okada and K. Kuyama, "Motion of rolling piston in rotary compressor", Proc. Purdue Compressor Tech.Conf.,1982.
- (3) T. Yanagisawa, T. Shimizu, I. Chu and K. Ishijima, "Motion analysis of rolling piston in rotary compressor",Proc. Purdue Compressor Tech. Conf.,1982.
- (4) T. Hirahara and O. Ohinata, "An Analysis of cylinder overpressure using the method of characteristics", Proc. Purdue Compressor Tech. Conf.,1982
- (5) K. Sakaino et al., "Some approaches towards a high efficiency rotary compressor", Proc. Int. Compressor Engineering Conf. at Purdue,1984.
- (6) K. Sakaino, K. Kawasaki and Y. Shirafuji, " The study of dual cylinder rotary compressor", Proc. Int. Compressor Engineering Conf. at Purdue,1986.

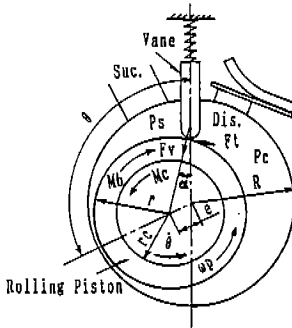


Fig. 1 Schematic view, Forces and Moments acting on Rolling Piston and Vane

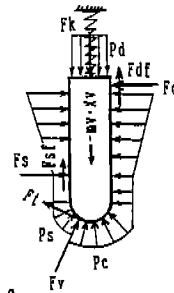


Fig. 2 Forces acting on Vane

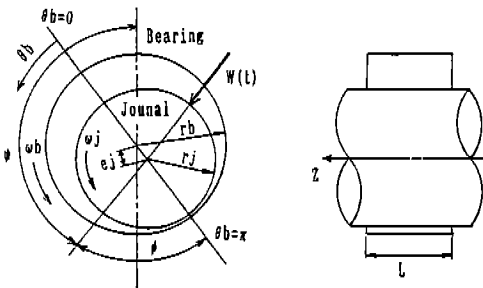


Fig. 3 Model of journal bearing

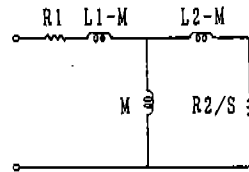


Fig. 4 Equivalent circuit for induction motor

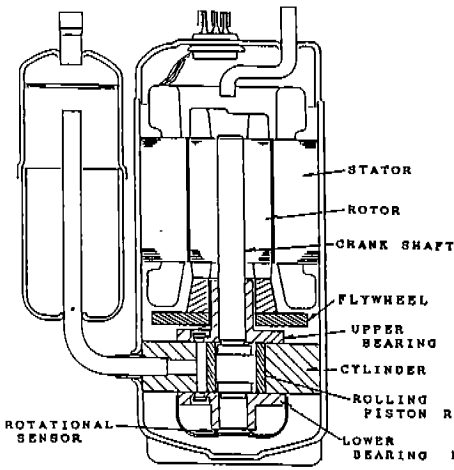


Fig. 5 Section view of experimental model for single-cylinder type

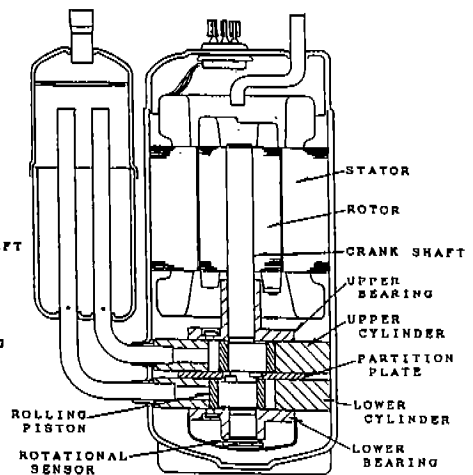


Fig. 6 Section view of experimental model for dual-cylinder type

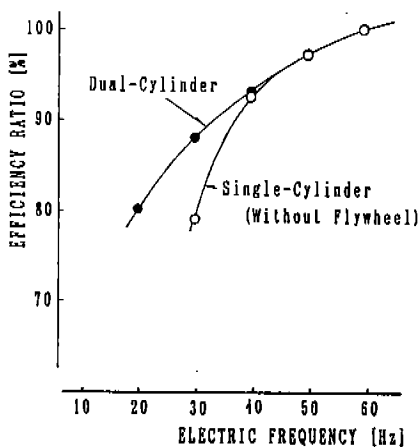


Fig. 7 Efficiency comparison

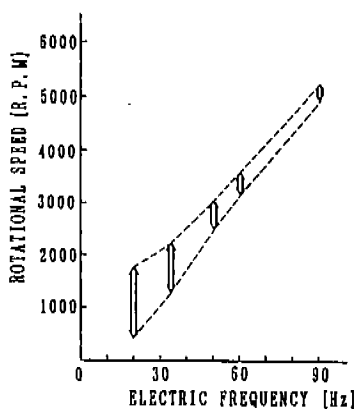


FIG. 8 Rotational-speed fluctuations of a conventional single-cylinder compressor

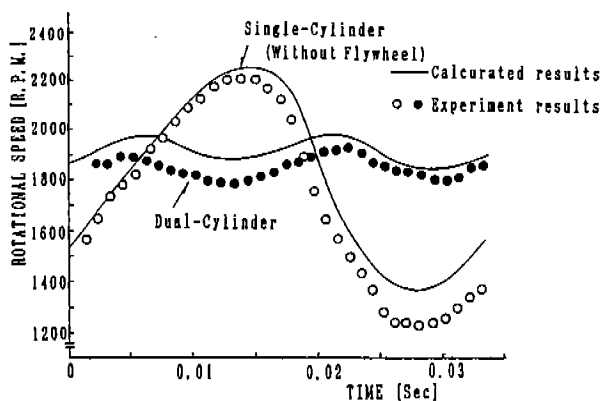


Fig. 9 The rotational-speed fluctuations at 34Hz frequency operation



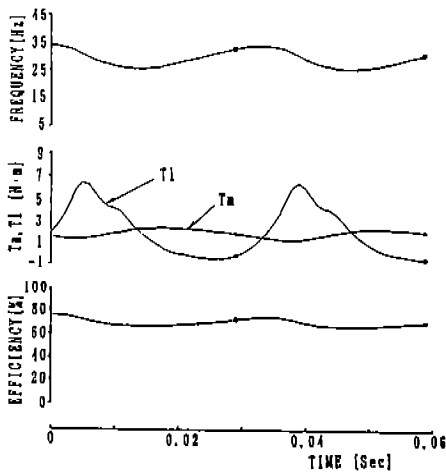


Fig. 10 Analytical results

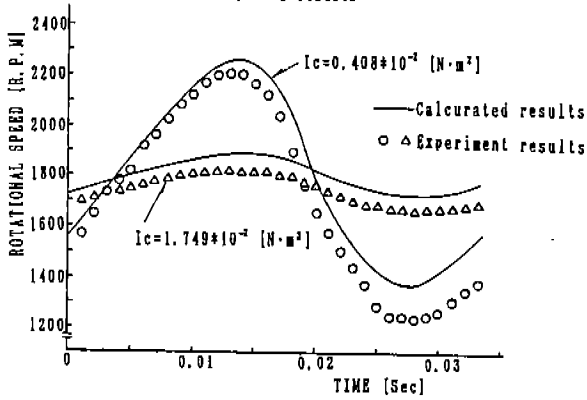


Fig. 11 The effect of flywheel at 34Hz frequency operation

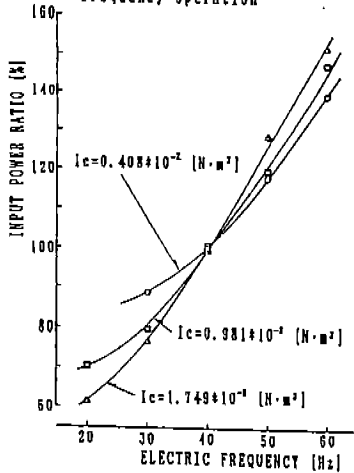


Fig. 12 The effect of flywheel on input power

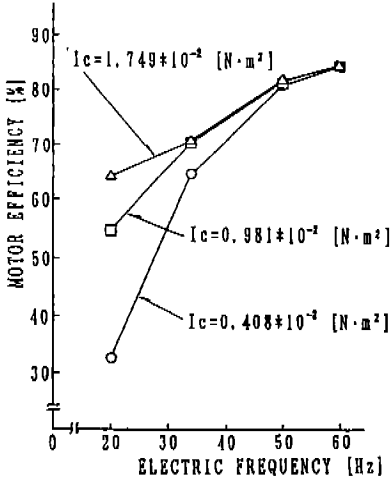


Fig. 13 The effect of inertia moment on motor efficiency

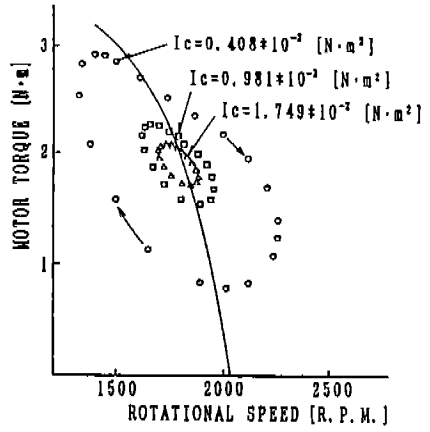


Fig. 14 Instantaneous rotation and torque at 34Hz frequency operation

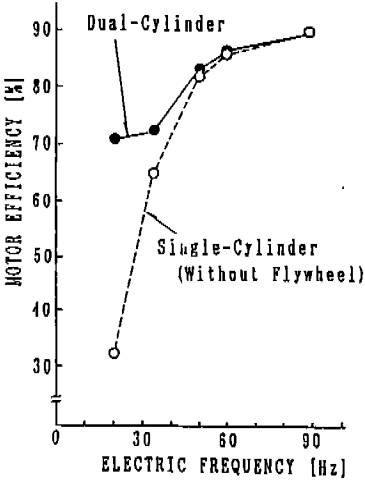


Fig. 15 The effect of load fluctuations on motor efficiency

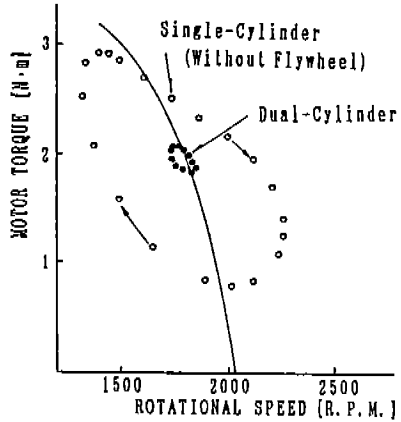


Fig. 16 Instantaneous rotation and torque at 34Hz frequency operation